

HUMA



41st Annual VFS Student Design Competition

Multi-Mission Modular UAS for Disaster Relief

Sponsored by:



UNIVERSITY OF
MARYLAND

Alfred Gessow Rotorcraft Center
Department of Aerospace Engineering
University of Maryland
College Park, MD 20742 U.S.A.



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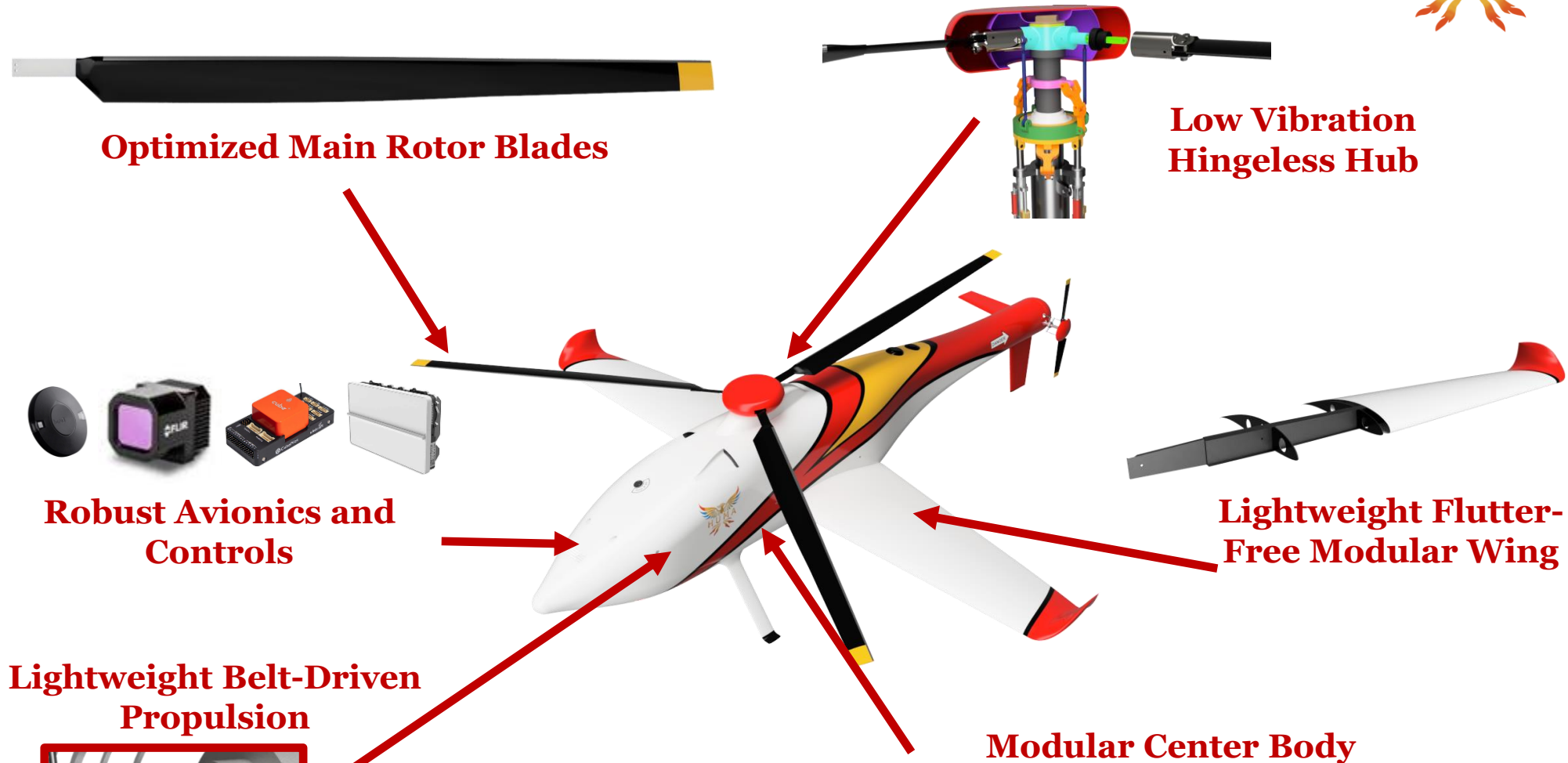
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To the Vertical Flight Society:

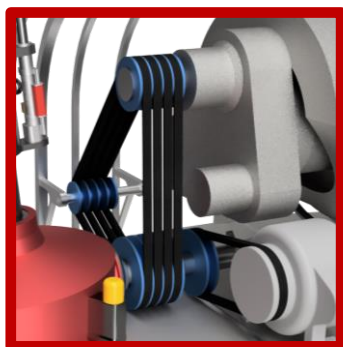
The members of the University of Maryland Graduate Student Design Team hereby grant VFS full permission to distribute the enclosed Executive Summary and Final Proposal for the 41st Annual Design Competition as they see fit.

Thank you,
The UMD Graduate Design Team

Huma: The Bird that Never Alights



Lightweight Belt-Driven Propulsion



GTOW	160 kg (353 lbs)
Installed Power	37 kW (50 hp)
Rotor Radius	1.65 m (5.4 ft)
Disk Loading	203 N/m ² (4.25 lb/ft ²)

Auxiliary fuel and wings 58 kg (128 lbs) split enable 13 hour loiter between two payload bays



Huma: Modular Load and Loiter



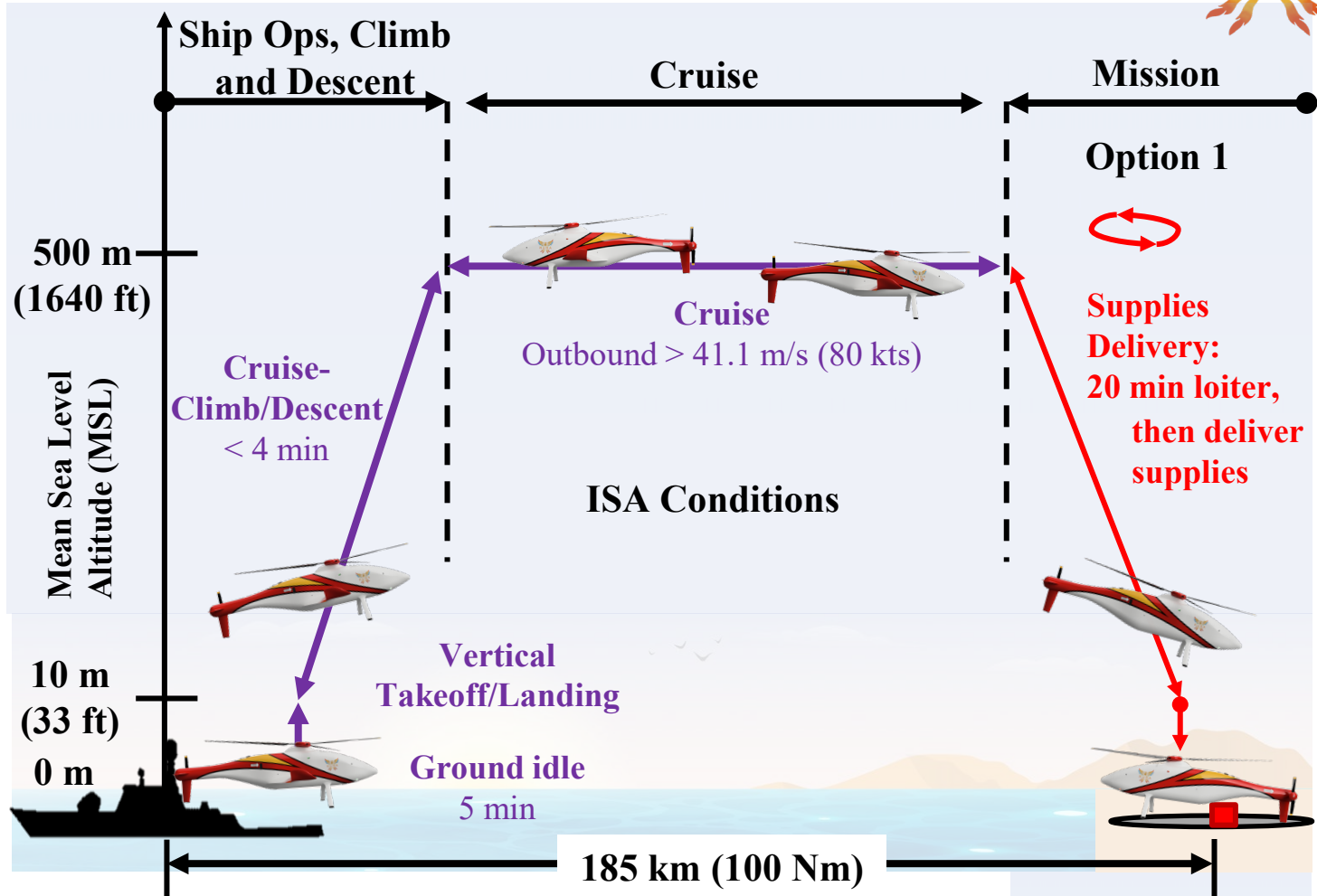
Soaring high above all for eternity, spreading hope by a mere glimpse of its shadow, the legendary *Huma* bird provides aid to all in need. It offers assistance without reservation, showering those below with gifts, blessings, and the touch of fortune.



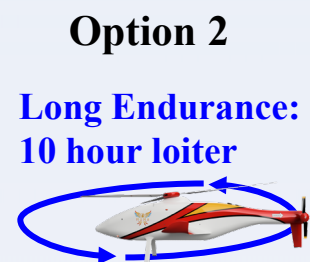
Huma, a reconfigurable **lift compounded single main rotor (SMR) helicopter**, developed by the UMD Graduate Design Team, is capable of exceptional flight time, able to loiter 185-km away from its takeoff point for **over 13 hours** before needing to return.

Huma is uniquely adaptable at 160 kg, able to quickly **remove its wings** and attach a heavy **55 kilograms** of lifesaving supplies to distribute to people in need. Huma can operate in challenging high-wind and gusty shipboard environments with a robust **hingeless hub**. Huma utilizes a **lightweight belt-driven transmission** and **low-drag three-point fixed landing gear** to maximize payload and minimize Jet-A fuel burn. An advanced flight control system with a **dynamic inversion** architecture, **error-resistant avionics suite**, and **vision-based ship deck landing** algorithm ensure situational awareness, stability, and reliability in all phases of flight. Whether at sea or over land, flying a long mission, or carrying a heavy payload, Huma remains steadfastly dependable and capable of successfully fulfilling any undertaking.

Exigent Dual Missions



	RFP Requirement	Huma
Long Endurance Loiter	10 Hours	13 Hours
Supplies Payload	50 kg (110 lb)	58 kg (128 lb)
Fuel Type	Jet-A	Jet-A
Empty Weight	-	Long endurance: 96.5 kg (213 lb) Supplies delivery: 92.5 (204 lb)



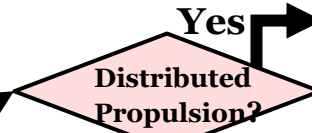
Configuration Selection



12 Configurations Considered



Preliminary Analysis



Configuration dropped: high weight, volume, and complexity

Qualitative Downselection for Detailed Analysis



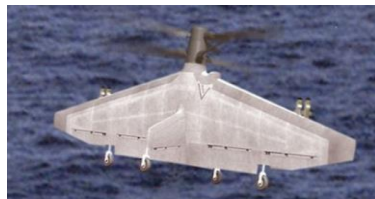
Single Main Rotor



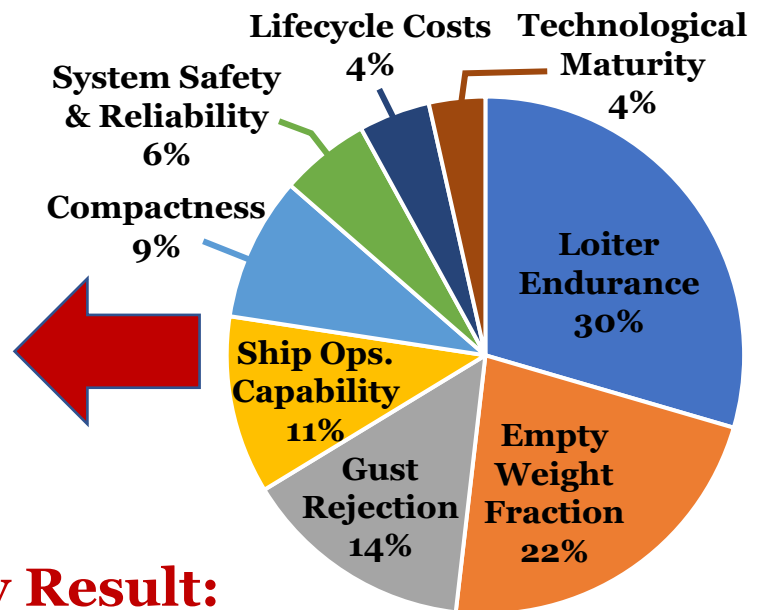
Lift+Thrust Compound



Lift Compound



Coaxial Winged Tailsitter



Comprehensive Trade Study Result:

Reconfigurable Lift Compounded SMR

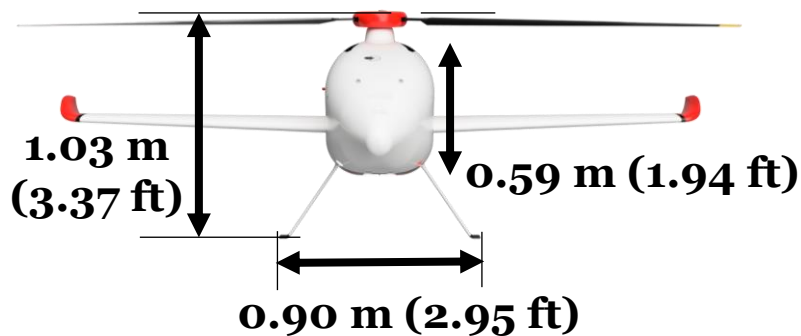
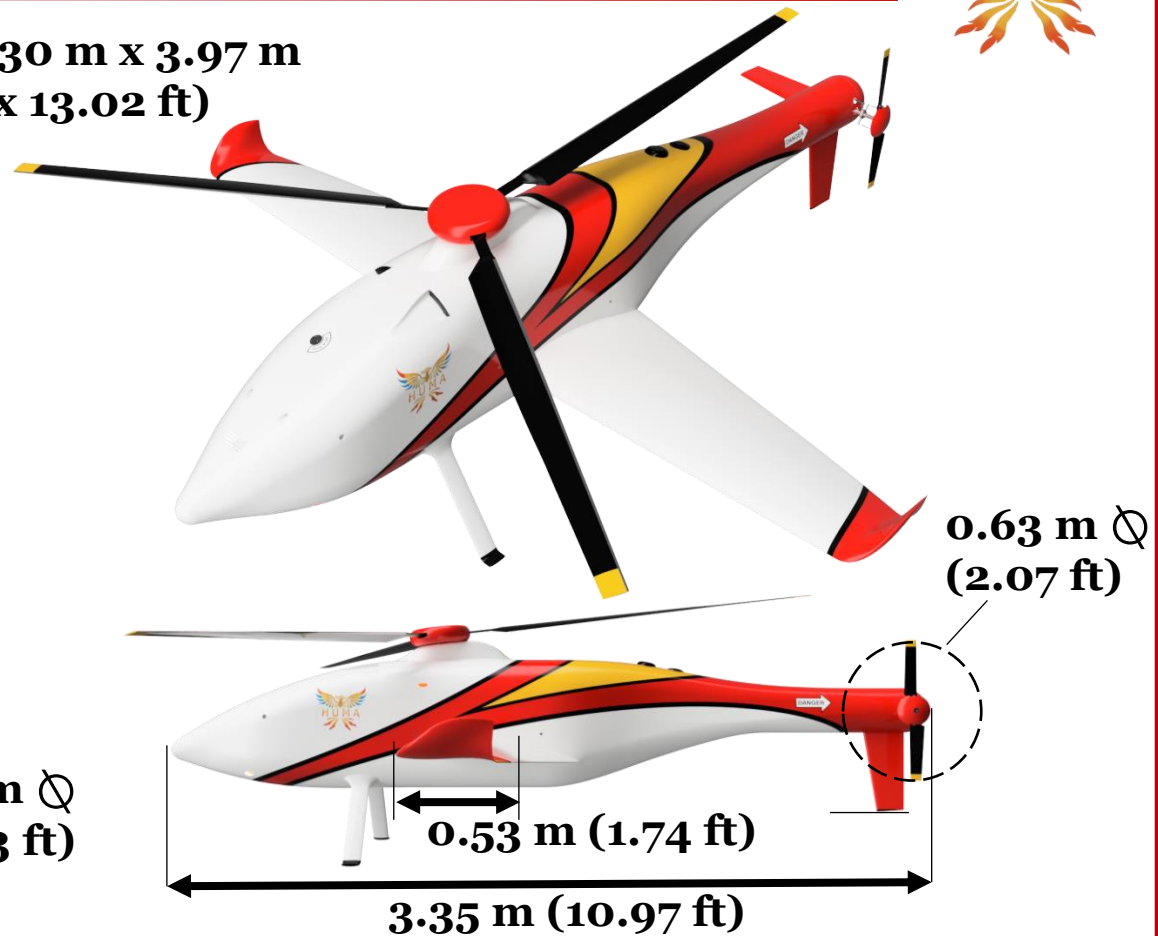
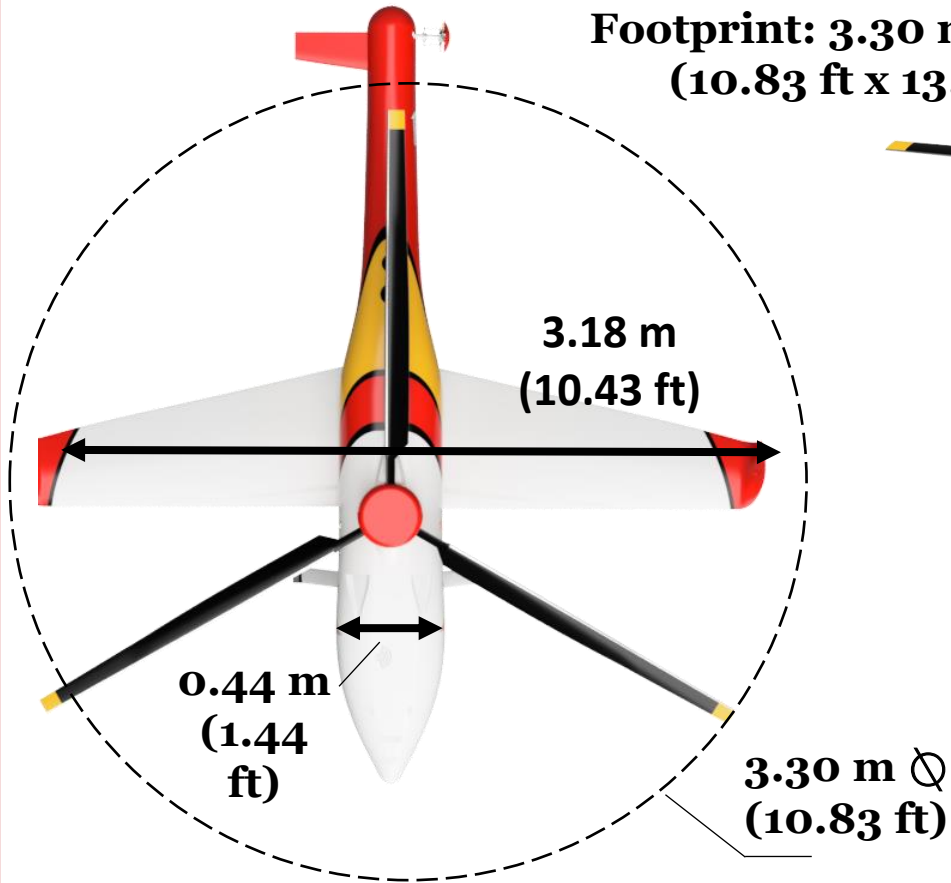
- Modular center body
- Removable wings
- High cruise L/D
- Low empty weight fraction
- Optimized dual-mission rotor blades



Huma: Size and Characteristics



**Footprint: 3.30 m x 3.97 m
(10.83 ft x 13.02 ft)**



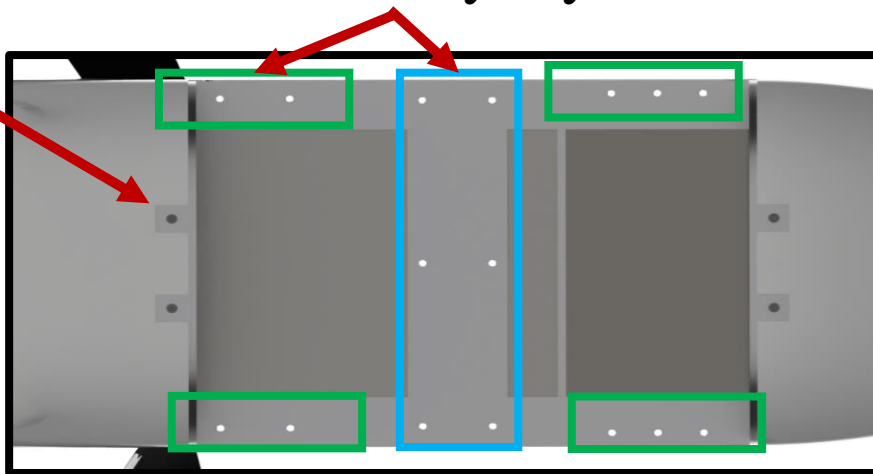
Characteristics	Huma
GTOW	160 kg (352 lbs)
Installed Power	37 kW (50 hp)
Disk Loading	203 N/m ² (4.25 lb/ft ²)
Payload	58 kg (128 lbs)
Loiter Endurance	13 hours

Modular Lift Compounding

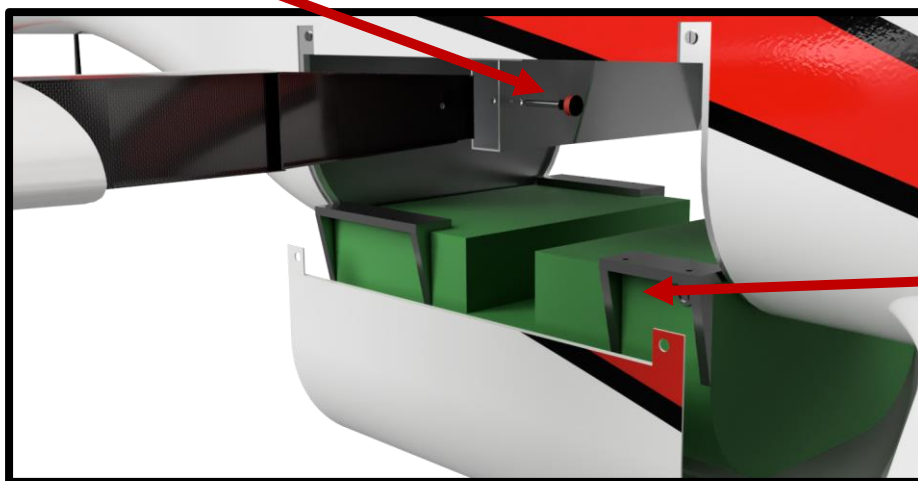


**Enclosure
skin
attachment
using quarter
turn screws**

**Mounting hardpoints located
in the center body bay**

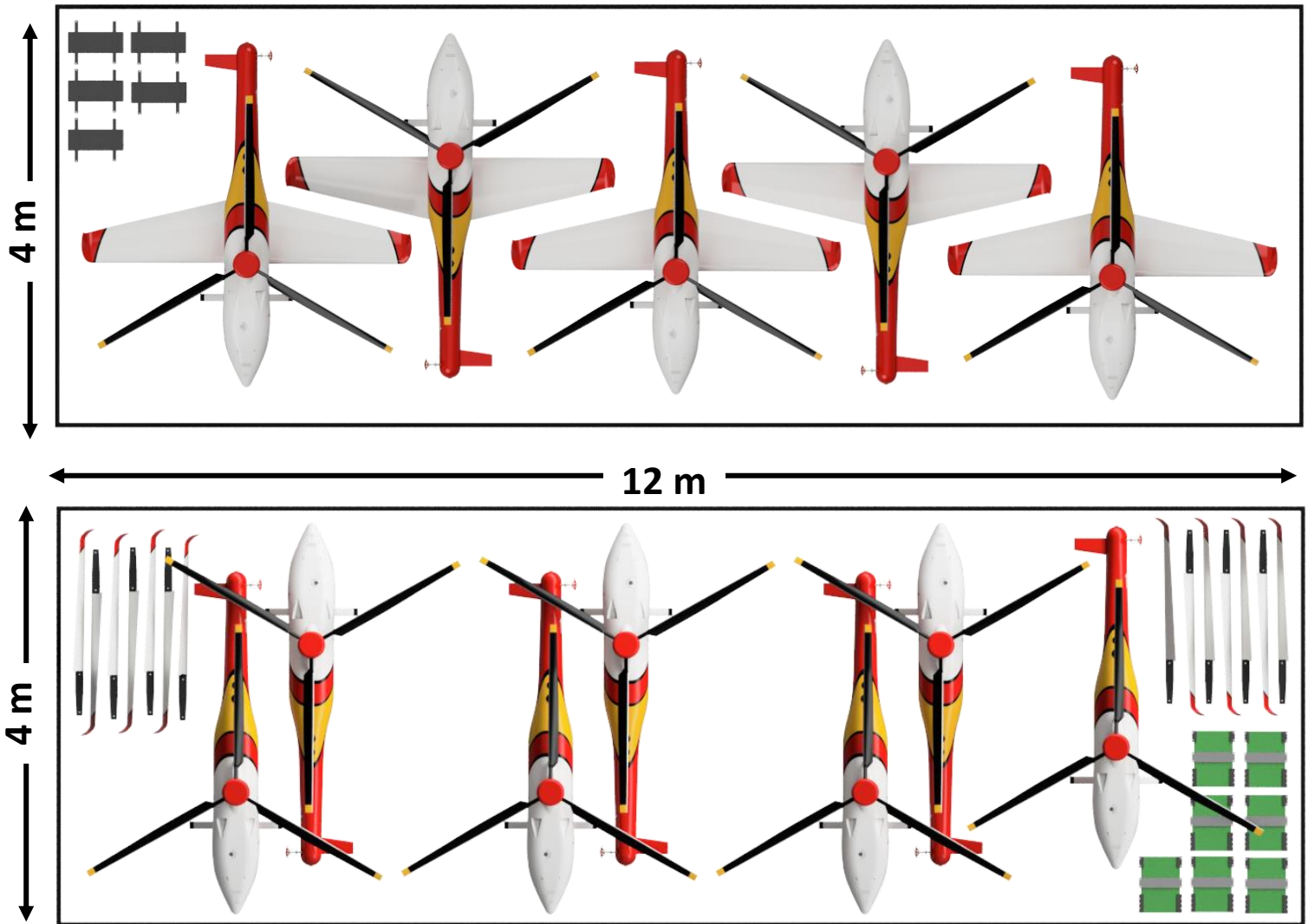


**Detachable
wing slots into
mounting box**



**Add-on
fuel tank
(35.4 L,
9.35 gal)
with
mounting
frame**

Compact and Portable

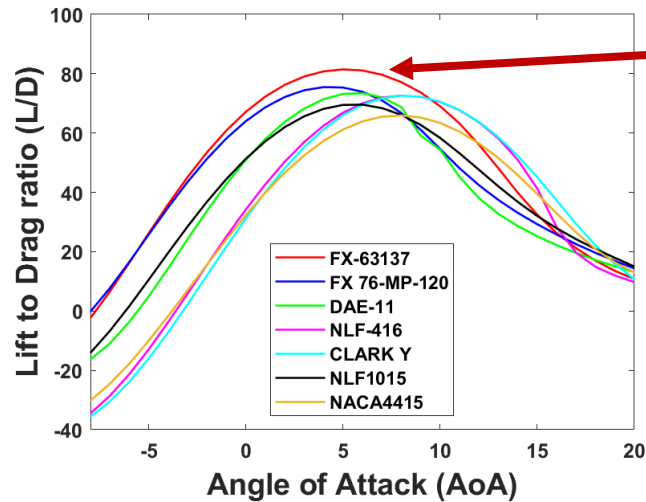


**5 with wings &
7 with wings on exterior racks**



**Loading &
refueling
requires
only one
kneeling
person**

Slender Flutter-Free Detachable Wing



14% t/c FX-63137 Airfoil

**Wing Weight:
1.97 kg (4.43 lb)**

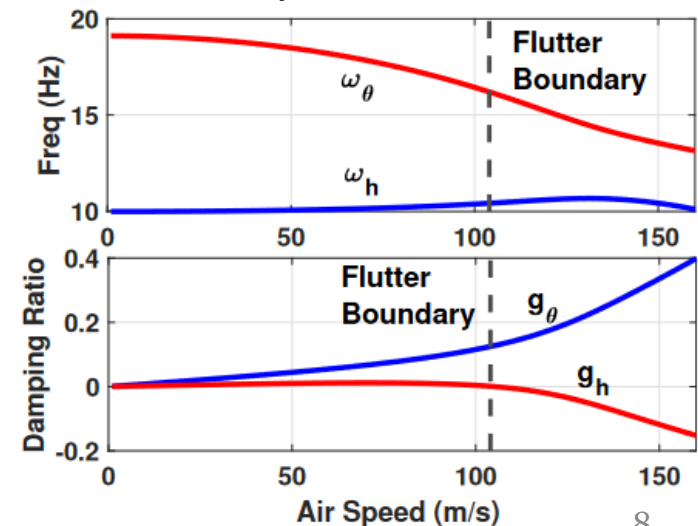
**Winglets decrease
recirculating vortices**

2:1 taper

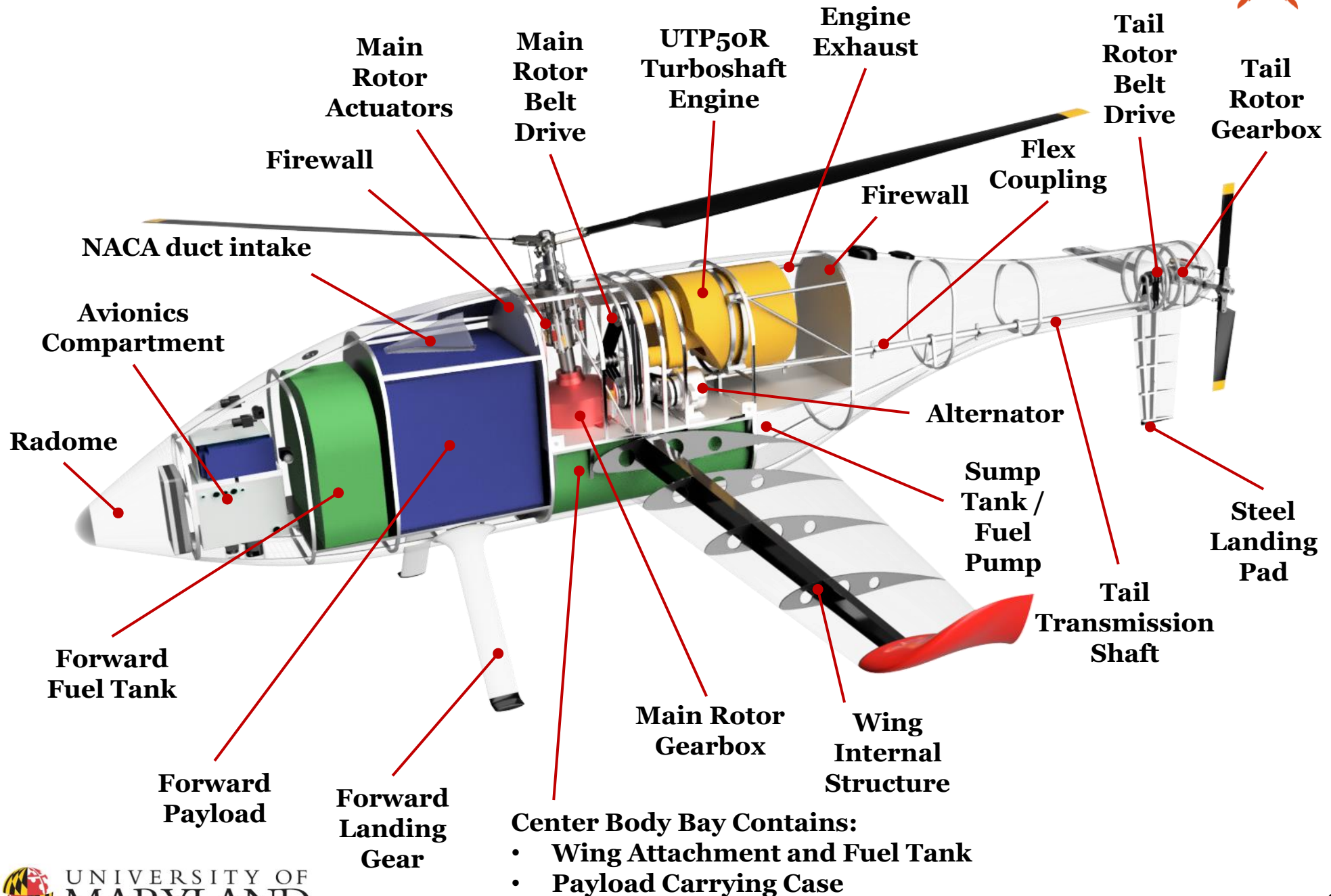
**2° dihedral
enhances stability**

Wing Spar Root Attachment

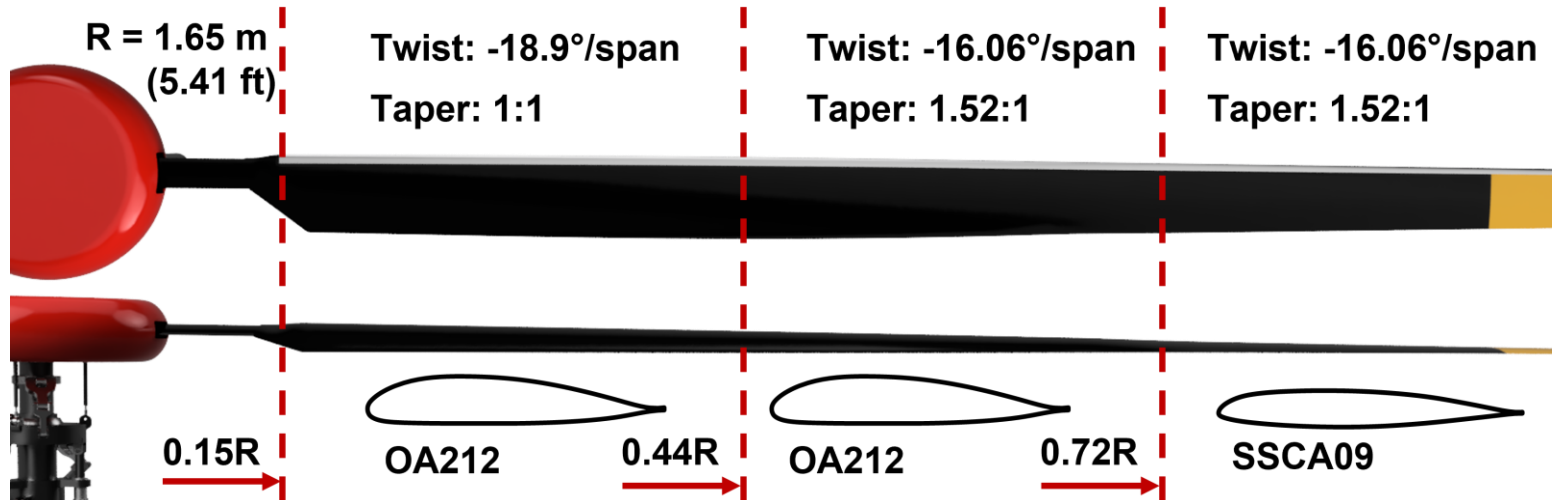
**Wings safe from flutter up
to 104 m/s (202 knots)**



Huma Internal Layout

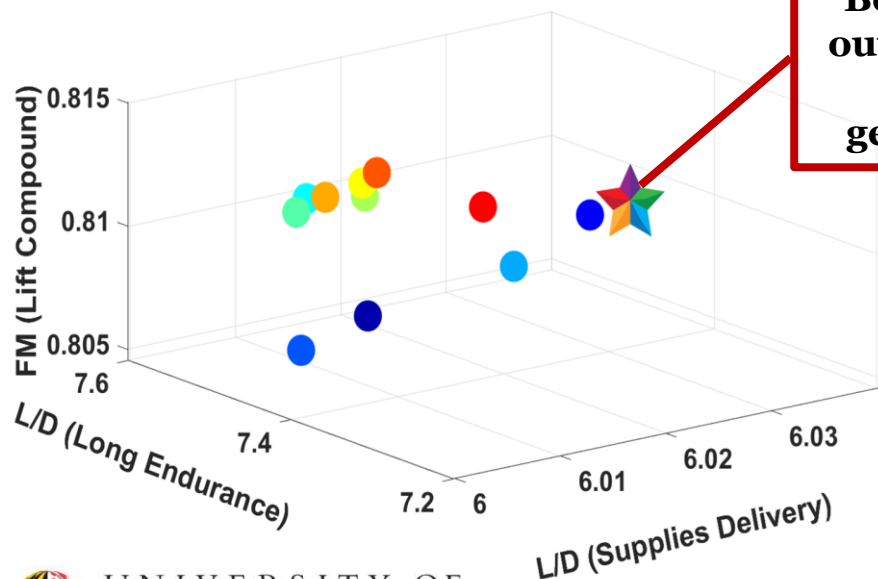


Main Rotor Blade Design



An Innovative Methodology

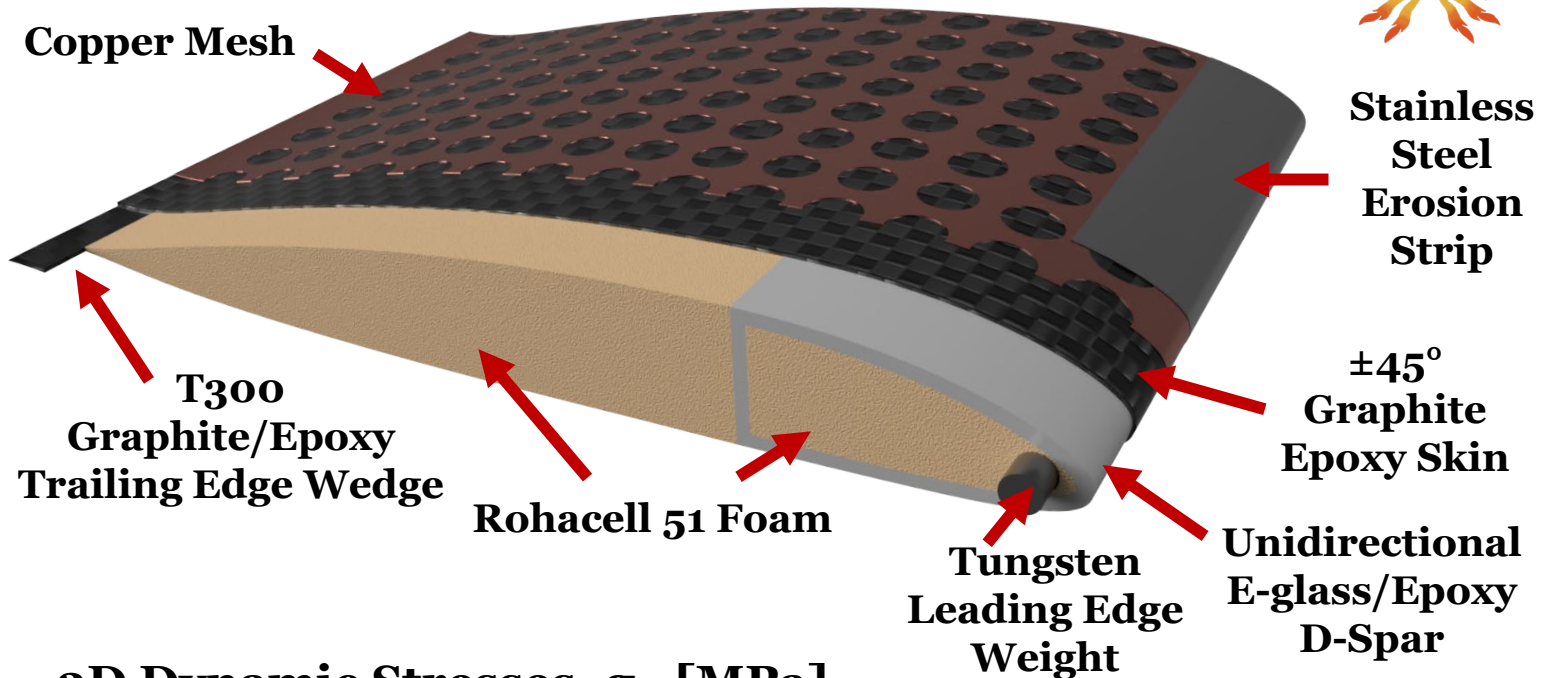
Genetic Algorithm to optimize blade for:
hover, loiter and cruise



Best design
out of 88000
tested
geometries

Mission	Segment	Performance	
Single Main Rotor	Hover	FM	0.81
		PL	15 lb/Hp
	Cruise	L/D	6
	Loiter	L/D	7.5
Lift Compound	Hover	FM	0.80
		PL	15 lb/Hp
	Cruise	L/D	6
	Loiter	L/D	7.5

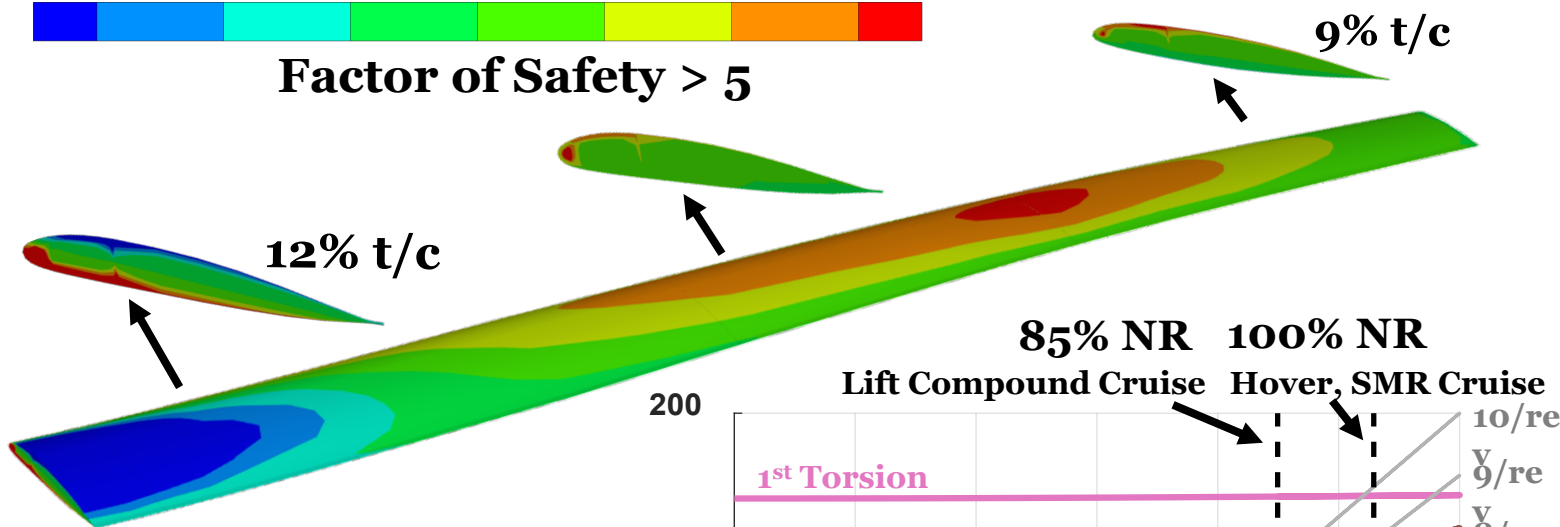
Blade Structural Design



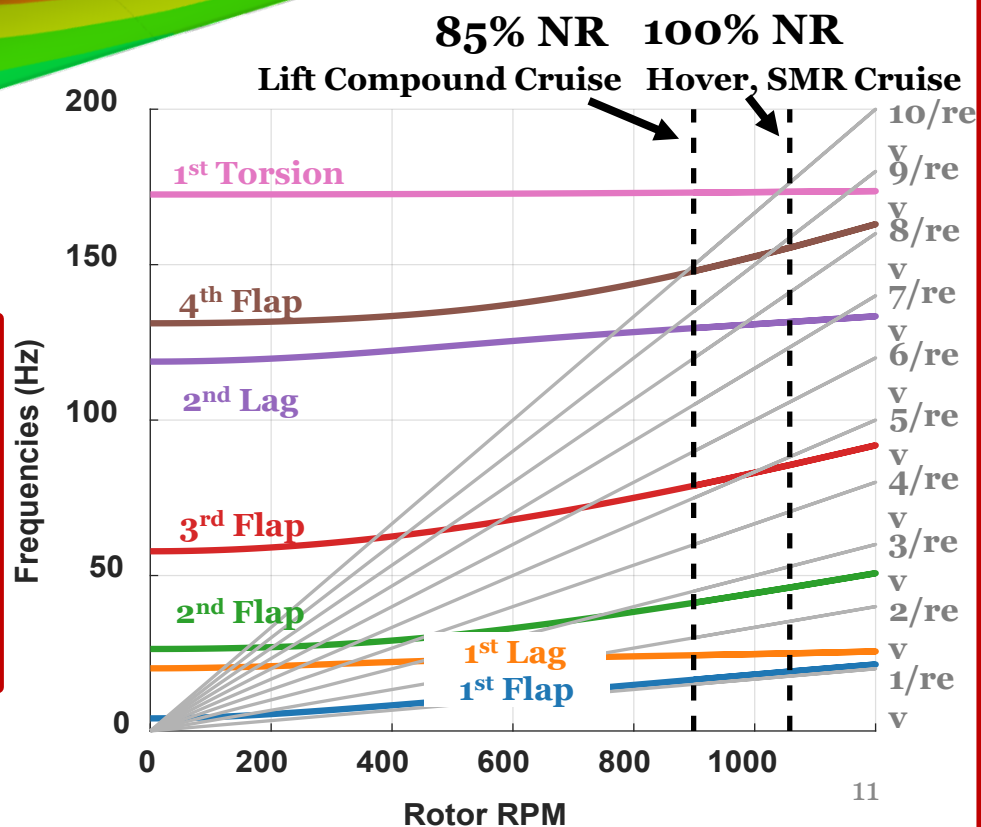
3D Dynamic Stresses, σ_{11} [MPa]



Factor of Safety > 5

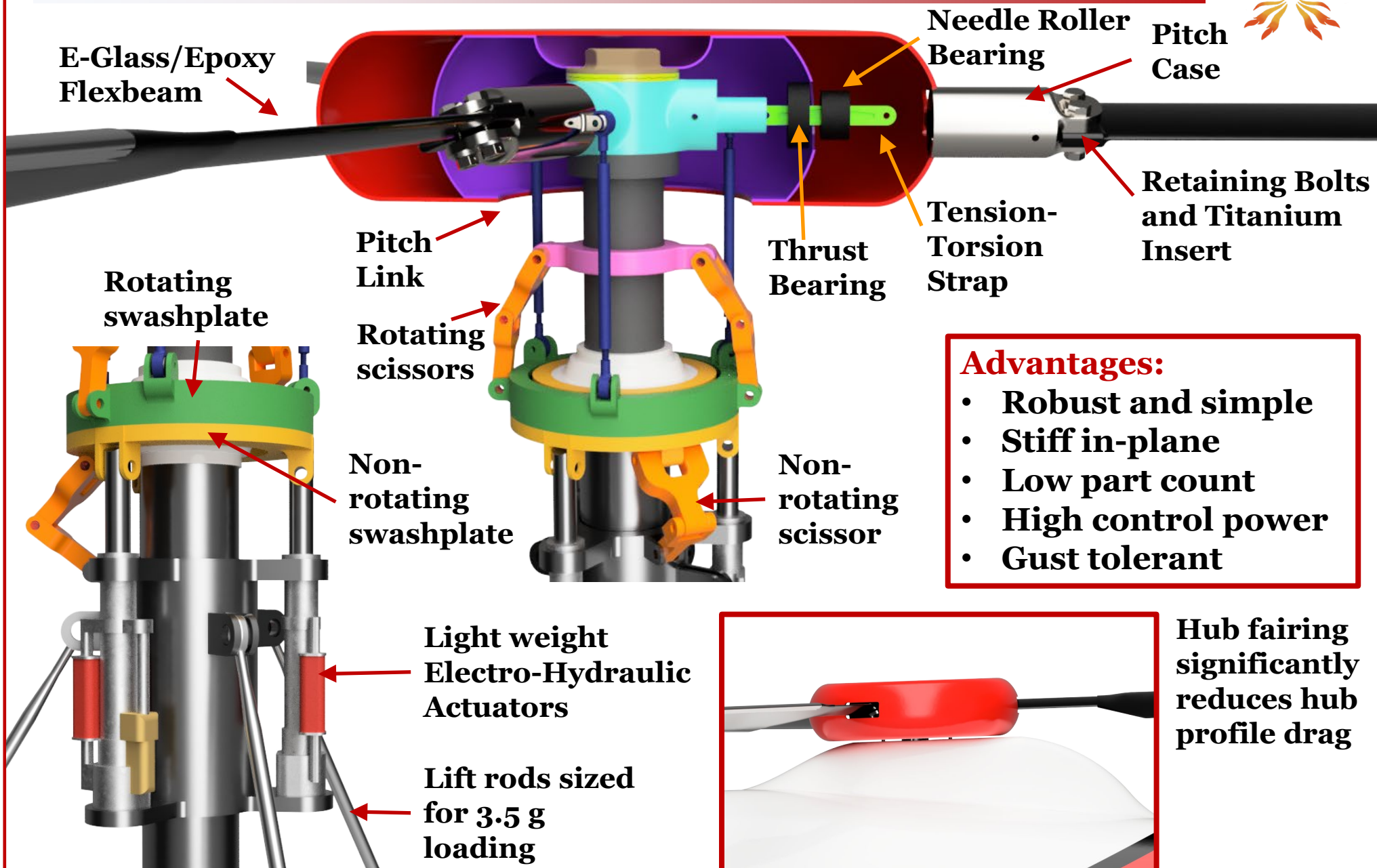


Hover
 Flap: 1.08/rev
 Lag: 1.42/rev
Cruise
 Flap: 1.10/rev
 Lag: 1.63/rev



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MARYLAND

Low Vibration Hingeless Hub



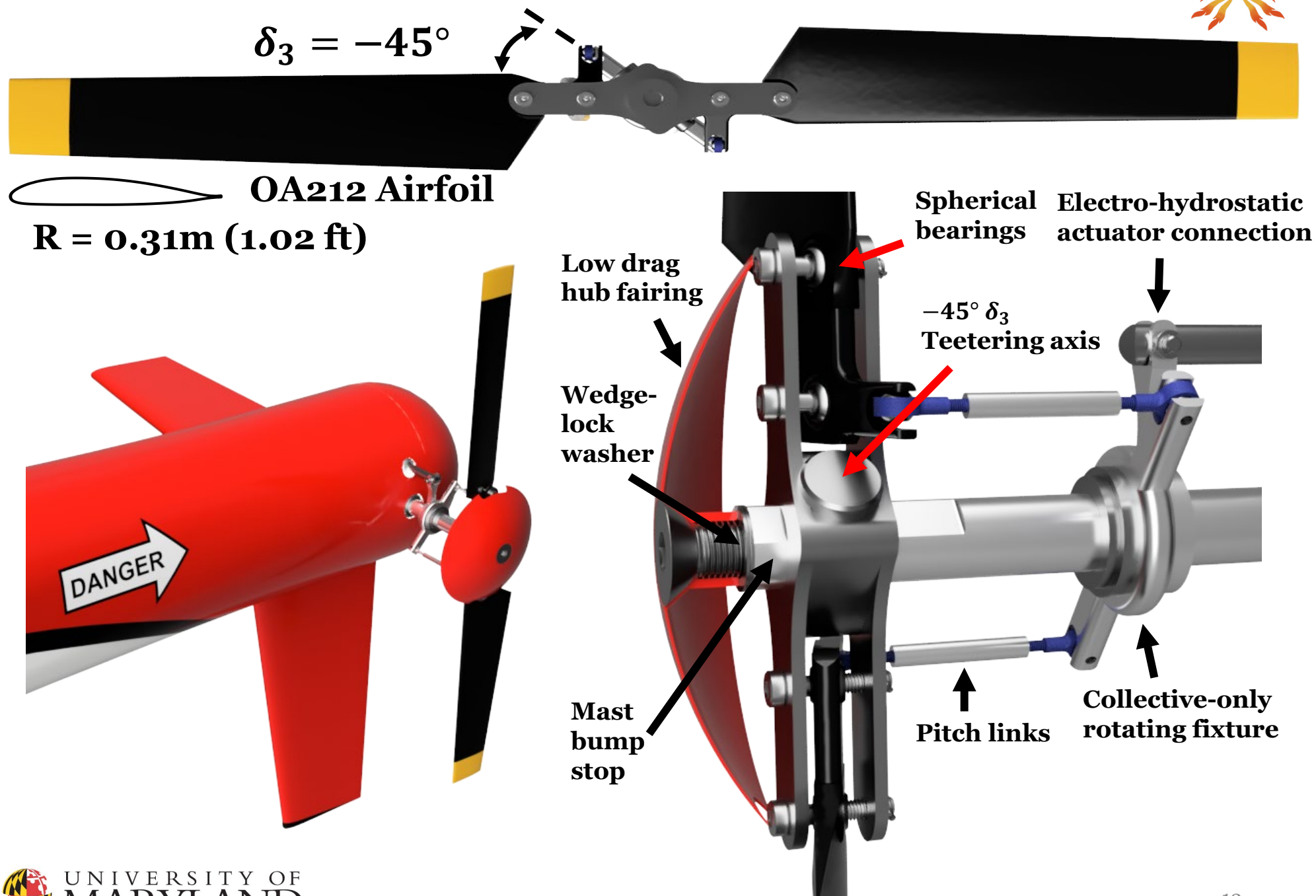
Advantages:

- Robust and simple
- Stiff in-plane
- Low part count
- High control power
- Gust tolerant



Hub fairing significantly reduces hub profile drag

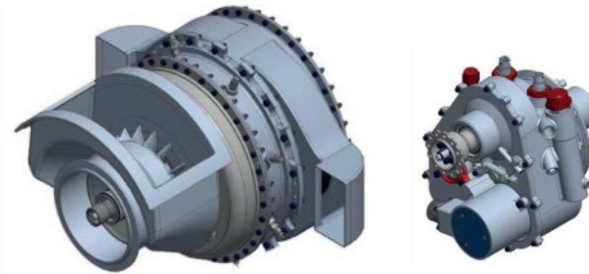
High Gust Tolerant Tail Rotor



Compact Belt-Driven Transmission



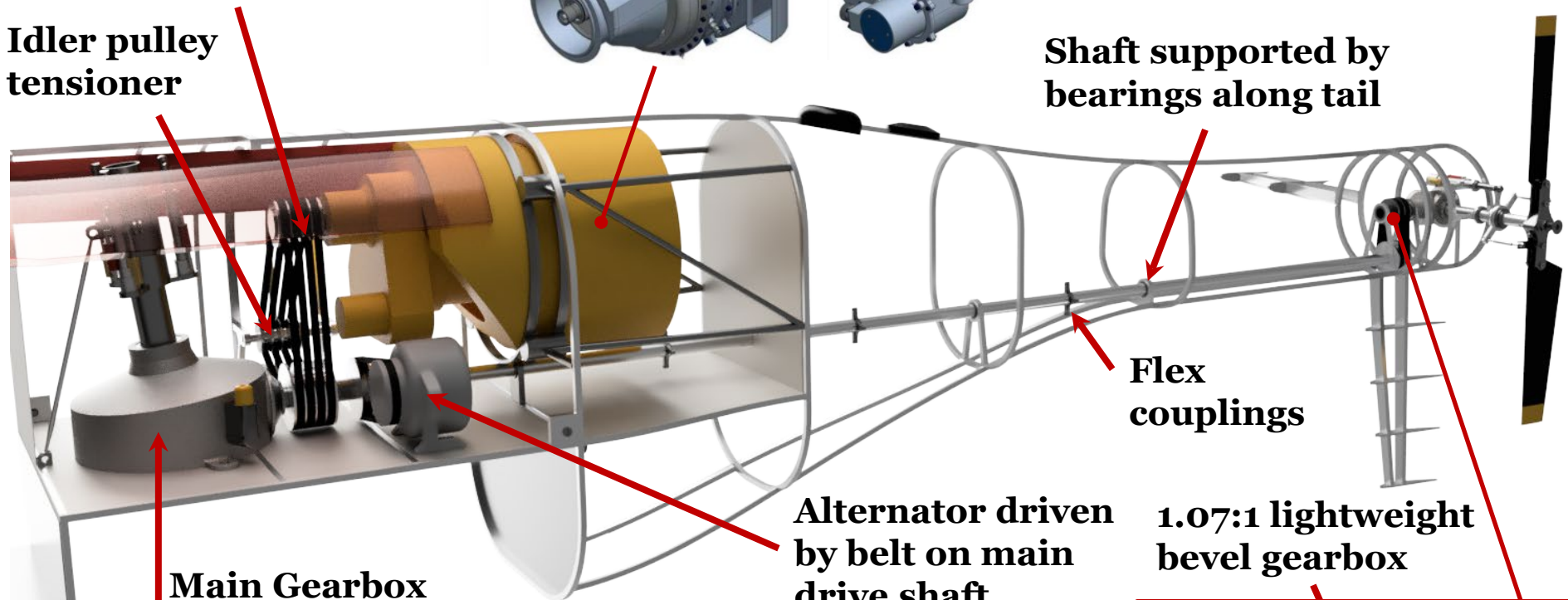
4x Optibelt XPZ-9JX belts with a reduction of 1:1.43



UTP50R Turboshaft:
37.23 kW (50hp)

Idler pulley tensioner

Shaft supported by bearings along tail



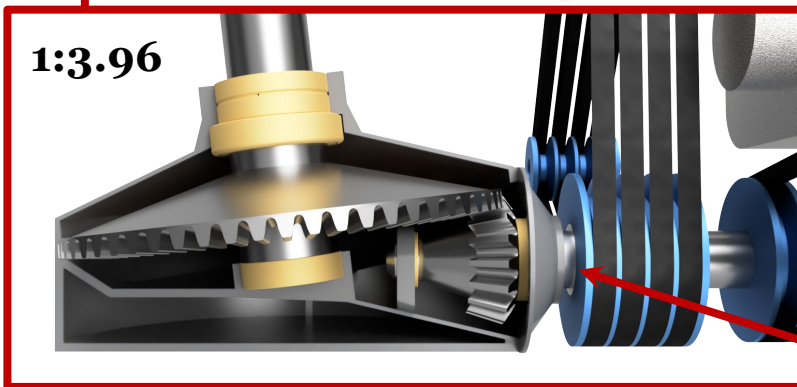
Main Gearbox

Flex couplings

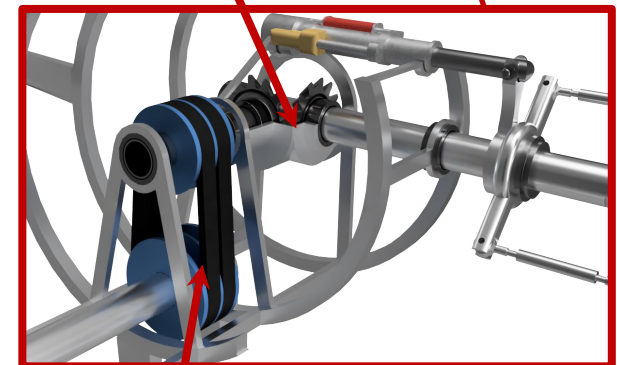
Alternator driven by belt on main drive shaft

1.07:1 lightweight bevel gearbox

1:3.96



Sprag clutch inside driver pulley

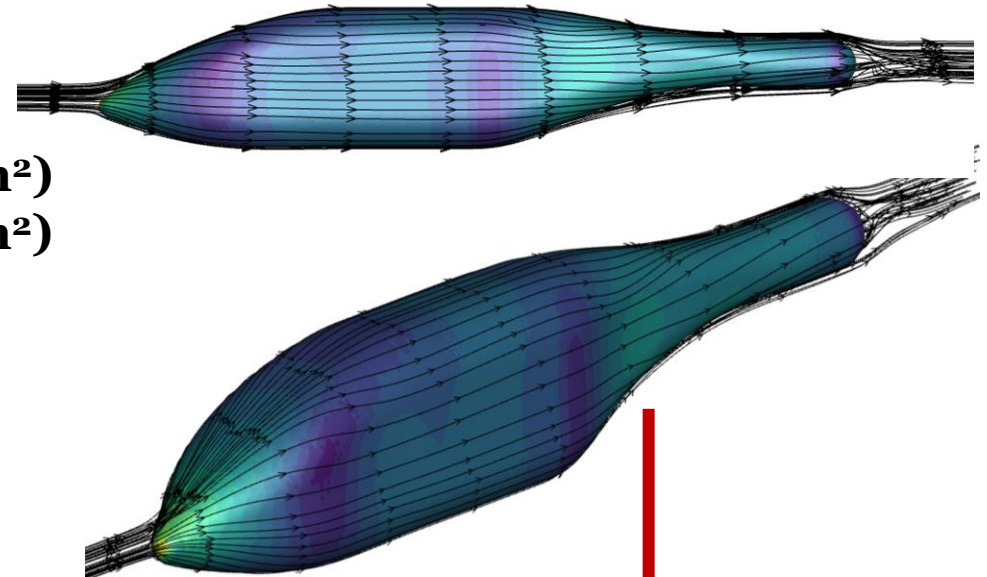


1.22:1 belt reduction reduces transmission weight

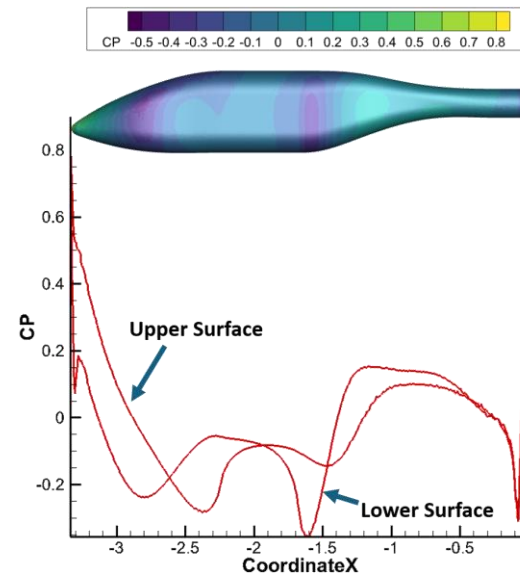
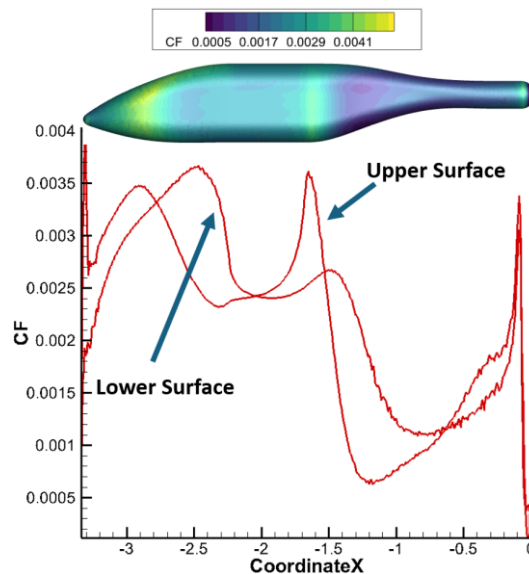
RANS CFD Based Aerodynamic Design



- A streamlined design for fuselage, hub fairing, and landing gear
- Low Flat Plate area
 - Supplies Delivery 1.31 ft² (0.1218 m²)
 - Long Endurance 1.53 ft² (0.1424 m²)



Hub Fairing



**Low adverse
pressure gradient**

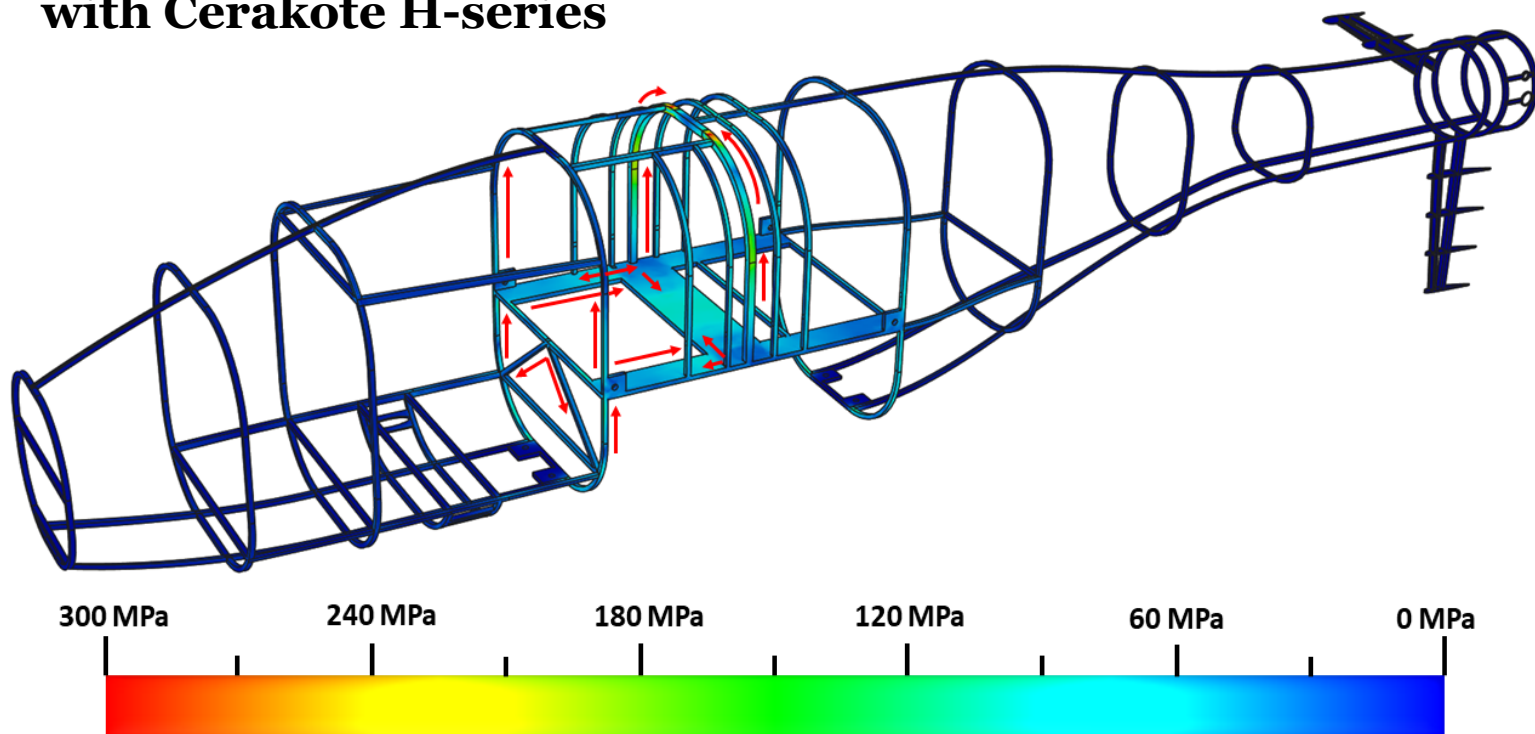
**No flow
separation**

Airframe and Landing Gear



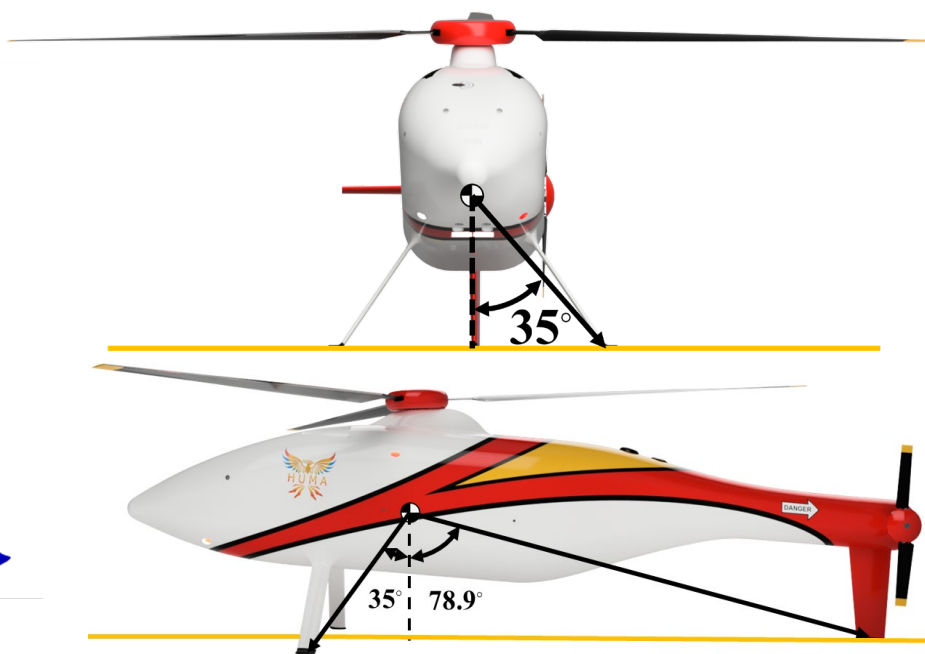
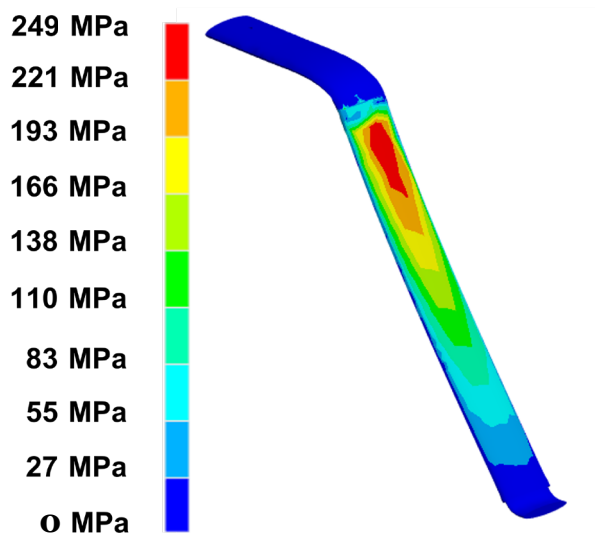
Designed according to NAVY AR56 requirements

Marinized corrosion-resistant airframe coated with Cerakote H-series



High Factor of Safety (1.71)

Three-point landing gear stable from dynamic rollover



Avionics Tailored for Shipboard Operations



Multiple sensors and onboard processing support full autonomy

SATCOM

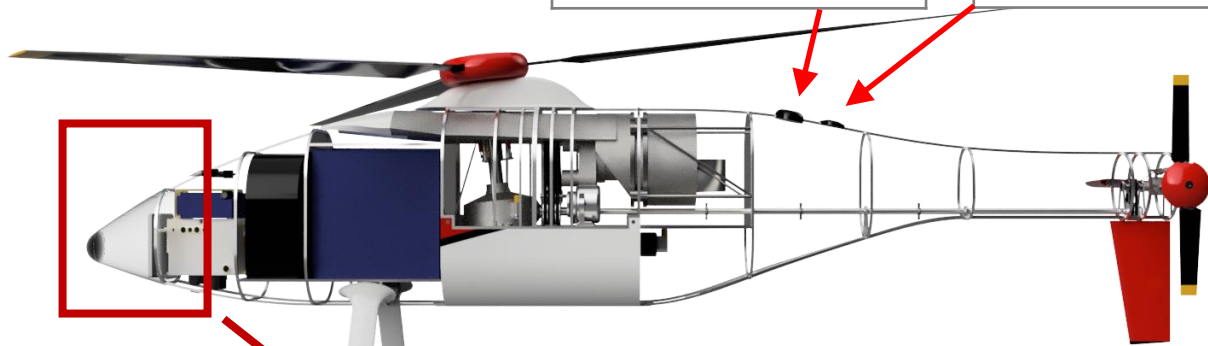


Communication beyond line-of-sight

GNSS



< 2.5 m position accuracy



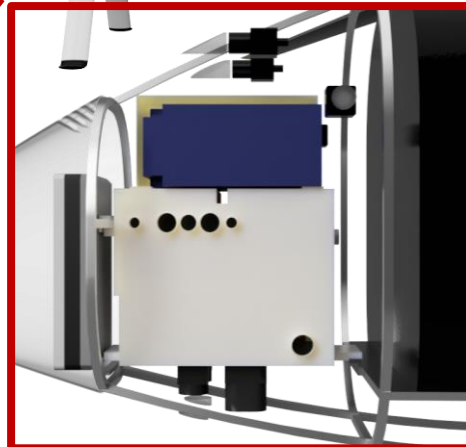
Sense-and-Avoid



Front- and side-facing cameras



Radar



Ground/Ship Landing Optical Navigation



Downward-facing cameras

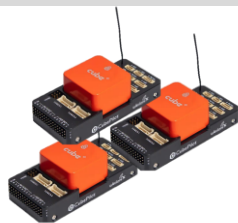


Thermal cameras

Internal Processing Components

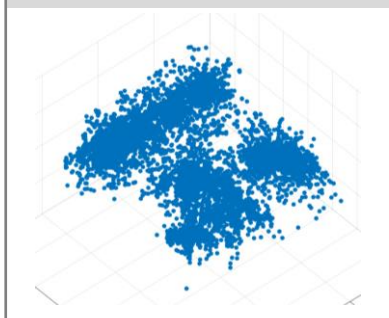


Jetson AGX Orin embedded computer

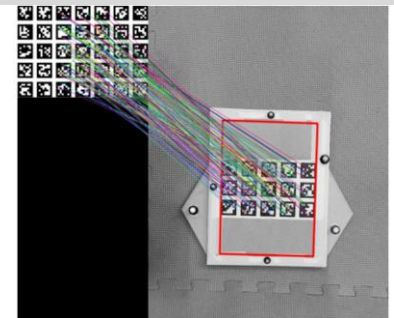


Triple-redundant flight controllers

3D cloud of features



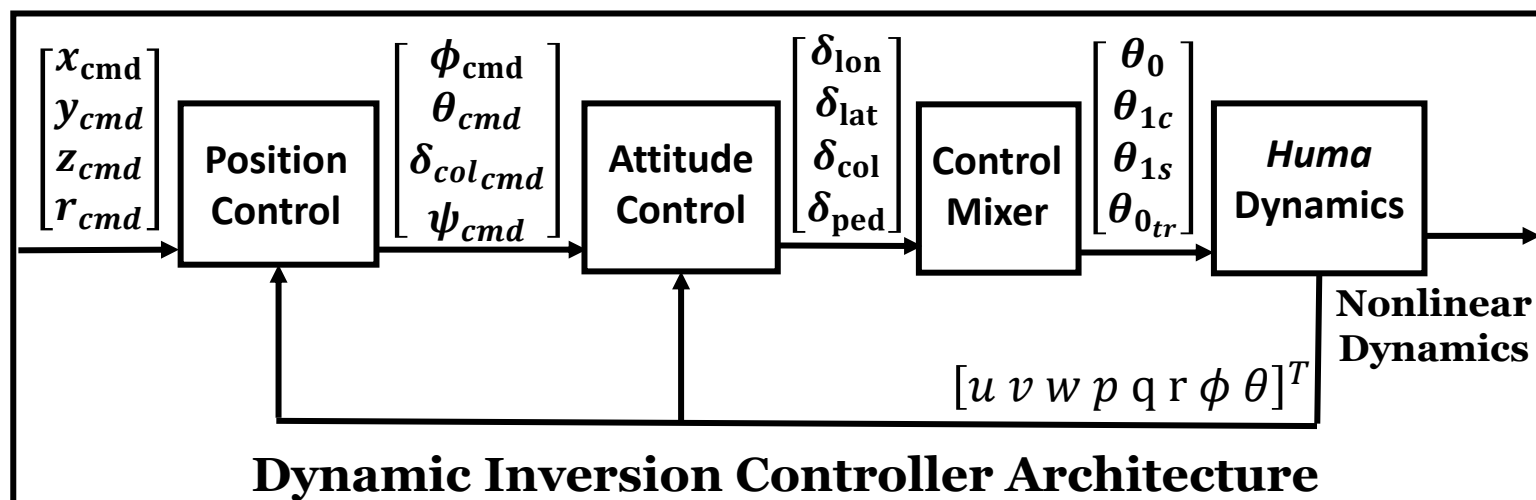
Vision based featured detection



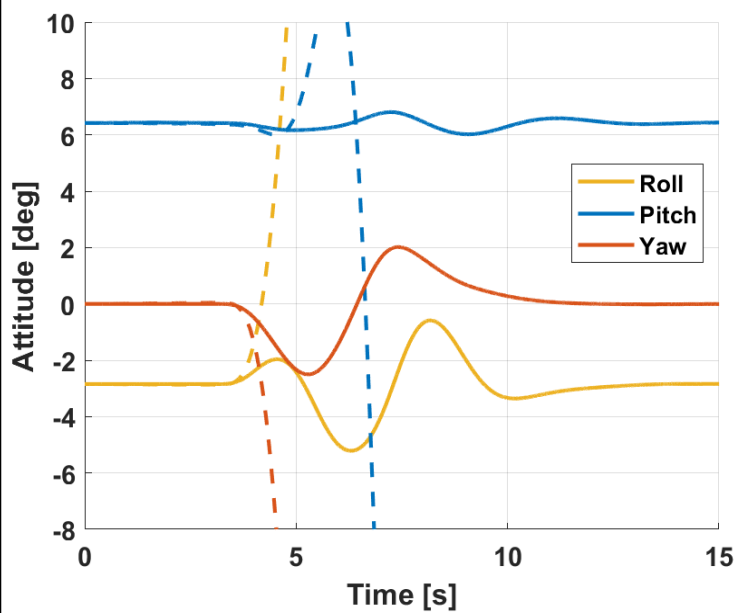
Multi-layered Dynamic Inversion Flight Controller



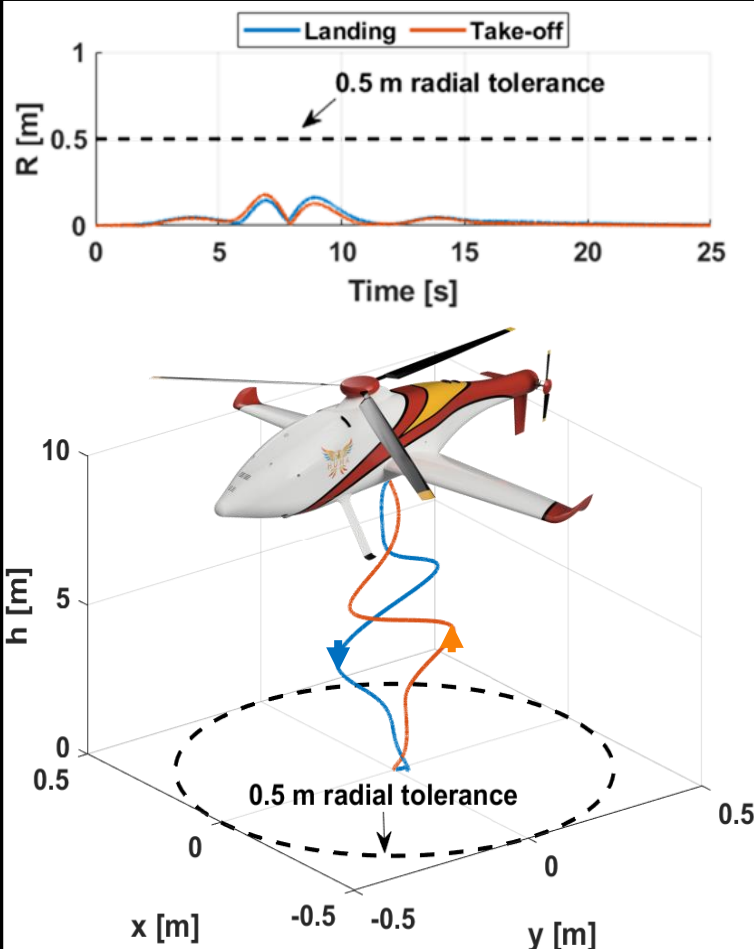
- Position control with Attitude Command Attitude Hold (ACAH) controller in hover
- Translational Rate Command (TRC) with ACAH controller in cruise



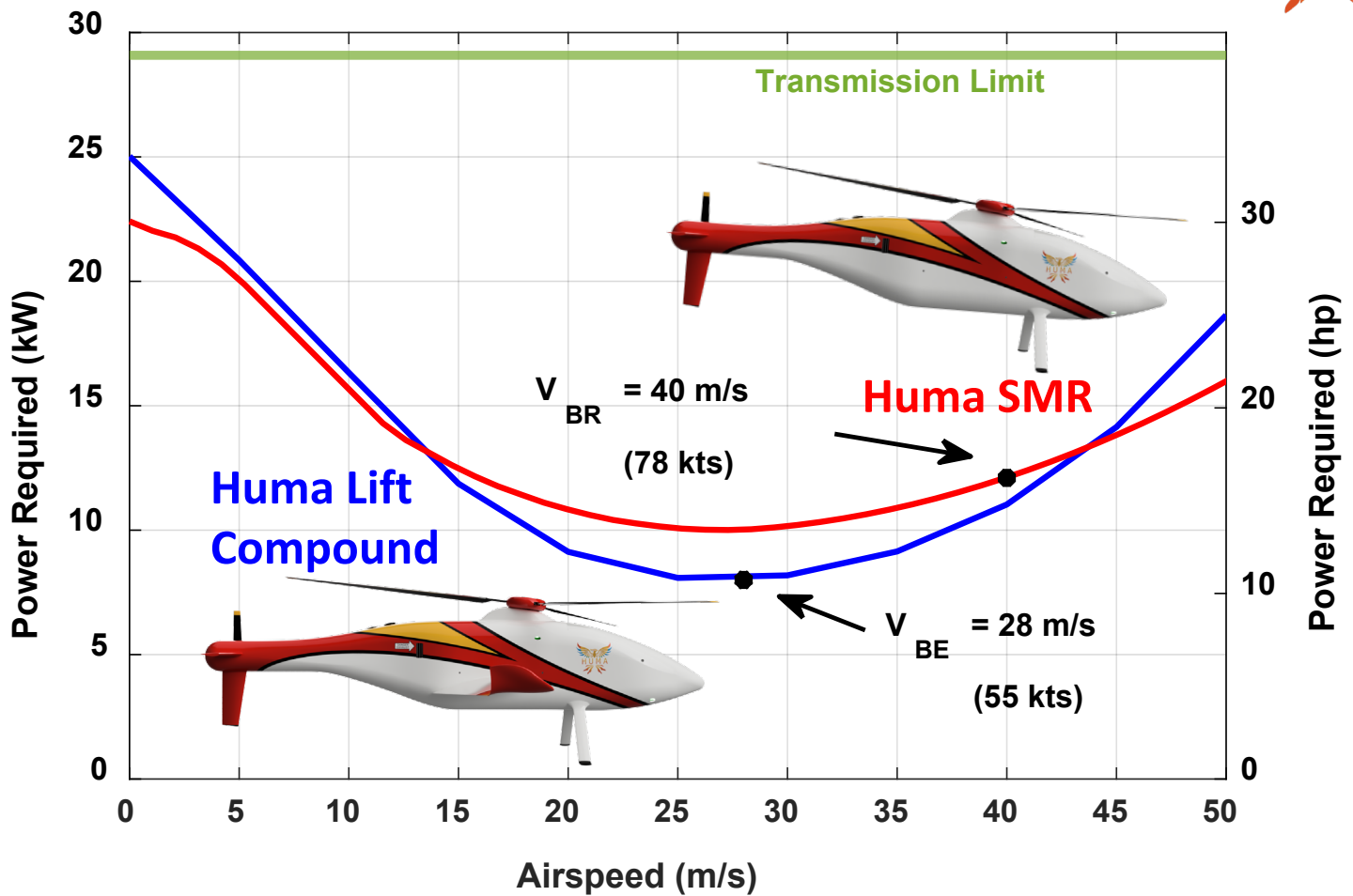
Gust rejection with stability augmentation, attitude and position control for ***launch and recovery***



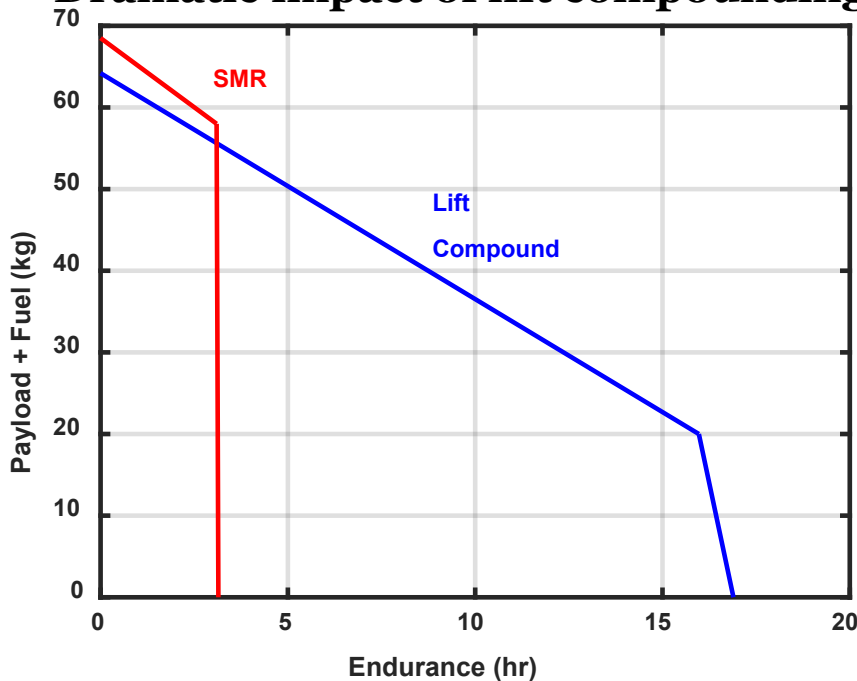
— — Uncontrolled — Controlled



Unprecedented Dual Mission Performance



Dramatic impact of lift compounding



Lift compound:

- Exceptional 13 hour loiter
- Maximum of 16 hour loiter without any payload

SMR:

- Heavy maximum payload of 69 kg (152 lb)

Multi-Mission Capability



Huma: A Modular UAV With Superior Dual-Mission Performance

Exceeds Mission Requirements

- 13 hour loiter endurance in long-range configuration
- 58 kg (128 lbs) payload capacity in supplies-delivery configuration

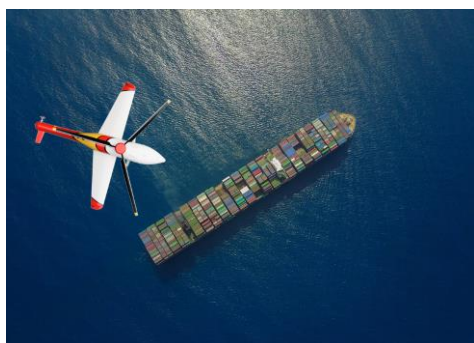
Affordable

- 187,000 USD estimated purchase price
- 205 USD maintenance and operational cost per flight hour



Applications for myriad missions

Maritime Surveillance and Reconnaissance



Agricultural Monitoring



Medical Delivery

